

CoMaLit – VI. Intrinsic scatter in stacked relations. The weak lensing AMICO galaxy clusters in KiDS-DR3

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ABSTRACT

Unbiased and precise mass calibration of galaxy clusters is crucial to fully exploit galaxy clusters as cosmological probes. Stacking of weak lensing (WL) signal allows us to measure observable–mass relations down to less massive haloes without extrapolation. We propose a Bayesian inference method to constrain the intrinsic scatter of the mass proxy in stacked analyses. The scatter of the stacked data is rescaled with respect to the individual scatter based on the number of binned clusters. We apply this method to the galaxy clusters detected with the AMICO (Adaptive Matched Identifier of Clustered Objects) algorithm in the third data release of the Kilo-Degree Survey. The results confirm the optical richness as a low-scatter mass proxy. Based on the optical richness and the calibrated WL mass–richness relation, mass of individual objects down to $\sim 10^{13} M_{\odot}$ can be estimated with a precision of ~ 20 per cent.

Key words: gravitational lensing: weak – methods: statistical – galaxies: clusters: general – cosmology: observations.

1 INTRODUCTION

Studies of number counts of galaxy clusters can put significant constraints on cosmological parameters (Vikhlinin et al. 2009; Mantz et al. 2015; Pacaud et al. 2018; Costanzi et al. 2019). Detection methods can recover large numbers of galaxy clusters with high levels of purity and completeness from optical bands (Rykoff et al. 2014; Oguri et al. 2018; Maturi et al. 2019), X-ray data (Pierre et al. 2016), or observations of the Sunyaev–Zeldovich effect (Bleem et al. 2015; Planck Collaboration XXVII 2016a). The constraining power of cluster abundance is strongly enhanced if the mass calibration is well understood and the mass–observable relation well known (Sartoris et al. 2016). An accurate and precise cosmological analysis requires the knowledge of both scaling parameters and intrinsic scatter, but recent efforts exploiting data from large surveys have been inconclusive (Planck Collaboration XXIV 2016b; DES Collaboration 2020), the suspect culprit being a biased knowledge of the observable–mass scaling relation.

The practical difficulties confront with a solid theoretical understanding of the main processes behind the scaling relations. In the self-similar scenario of structure virialization (Kaiser 1986; Giodini et al. 2013; Etori 2015), the mass is the driving property that informs every other halo property. Tight scaling relations in form of power

laws relate the cluster properties but non-gravitational processes or deviation from equilibrium can affect the scalings and introduce an intrinsic scatter, such that clusters with the same mass can have somewhat different optical richness or X-ray luminosity. Numerical simulations (Staneke et al. 2010; Fabjan et al. 2011; Angulo et al. 2012; Truong et al. 2018) and observations (Maughan 2014; Mantz et al. 2016; Sereno et al. 2020) show that the intrinsic scatter is approximately lognormal.

One of the main problems in cosmological analyses is the selection of a complete sample of galaxy clusters with well-measured masses. Weak lensing (WL) masses are regarded as reliable measurements but analyses of individual haloes are challenging due to low signal-to-noise detections. Accurate and precise results can be available only for either heterogeneous or small samples of massive objects (Applegate et al. 2014; Umetsu et al. 2014; Okabe & Smith 2016; Melchior et al. 2017; Sereno et al. 2017). Even with high-quality data, the analysis of small groups suffers from very large statistical uncertainties (Sereno et al. 2020; Umetsu et al. 2020). Furthermore, projection effects, triaxiality, and prominent substructures can bias the mass measurement (Rasia et al. 2012).

The signal of different galaxy clusters at fixed observables can be coherently added. This stacking technique allows to significantly enhance the signal of less massive haloes and to measure their average mass in a range that is out of reach for analyses of individual clusters (Johnston et al. 2007; Mandelbaum & Seljak 2007; Rozo, Wu &

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Schmidt 2011; Melchior et al. 2017; Simet et al. 2017). Results are very solid. Stacked WL masses and optical richnesses show tight correlations (Bellagamba et al. 2019; McClintock et al. 2019; Murata et al. 2019). However, the picture is still not complete, since most stacking analyses do not return the estimate of the intrinsic scatter, which is usually assumed to be negligible. Whereas the intrinsic scatter of stacked quantities can be negligible, the scatter of individual haloes is not and we need to know it for cosmological inference based on number counts.

Here, we tackle the problem of how to reconstruct the full information on scaling relations and intrinsic scatter from stacked data. As a study case, we apply the method to the galaxy clusters detected with the algorithm AMICO (Adaptive Matched Identifier of Clustered Objects; Bellagamba et al. 2018; Maturi et al. 2019) in Kilo-Degree Survey Data Release 3 (KiDS DR3; de Jong et al. 2013; Kuijken et al. 2015), a WL survey in the Southern hemisphere. This is the sixth in the CoMaLit (COMparing MASSES in LITerature) series of papers, wherein we have been applying Bayesian hierarchical procedures to studies of masses and scaling relations. The method can deal with heteroscedastic and possibly correlated measurement errors, intrinsic scatter, upper and lower limits, systematic errors, missing data, forecasting, time evolution, and selection effects. In the first paper of the series (CoMaLit-I; Sereno & Ettori 2015a), we considered the calibration of scaling relations and we assessed the level of intrinsic scatters in WL or X-ray mass proxies. In the second paper of the series (CoMaLit-II; Sereno, Ettori & Moscardini 2015), we introduced the Bayesian method to infer scaling relations and we applied it to WL clusters with measured SZ flux. The third paper of the series (CoMaLit-III; Sereno 2015) presented the literature catalogues of weak lensing clusters of galaxies, meta-catalogues of WL clusters. The fourth paper of the series (CoMaLit-IV; Sereno & Ettori 2015b) dealt with redshift evolution and completeness. The scalings of optical richness, X-ray luminosity, and galaxy velocity dispersion with mass were considered. In the fifth paper of the series (CoMaLit-V; Sereno & Ettori 2017), we dealt with efficient mass forecasting. The method was extended to multidimensional analyses in Sereno et al. (2019).

The paper is as follows. In Section 2, we discuss proxies, intrinsic scatters, and degeneracies that affect parameter recovery. The stacking technique is introduced in the framework of a Bayesian model in Section 3. The method to recover the intrinsic scaling relation from stacked data is presented in Section 4. In Section 5, we consider the optically detected clusters in the AMICO-KiDS-DR3 catalogue (Maturi et al. 2019). In Section 6, we review some results from the literature. Section 7 is devoted to some final considerations. In Appendix A, we present alternative expressions for the bivariate normal distribution of two scattered proxies. In Appendix B, we detail how systematic uncertainties are dealt with in the CoMaLit approach. In Appendix C, we provide information to reproduce the paper results.

1.1 Notation and conventions

As reference cosmological model, we assume a flat lambda cold dark matter universe with matter density parameter $\Omega_M = 0.3$ and Hubble constant $H_0 = 70 \text{ km s}^{-1} \text{ Mpc}^{-1}$.

The notation ‘log’ represents the logarithm to base 10 and ‘ln’ is the natural logarithm. Scatters in natural logarithm can be quoted as per cents. Throughout the paper, unless otherwise noted, we denote σ as the intrinsic scatter in log (decimal) quantities and use δ to represent log (decimal) measurement uncertainty.

Unless stated otherwise, central values and dispersions of the parameter distributions are computed using the biweighted statistics (Beers, Flynn & Gebhardt 1990) of the marginalized posterior distributions.

Computations were performed with the R package `lira` (Linear Regression in Astronomy).¹ As baseline, we consider the standard priors used throughout the CoMaLit series (see e.g. CoMaLit-IV).

2 PROXIES AND INTRINSIC SCATTER

In most astrophysical analyses, we have to deal with scattered proxies of an underlying property. Here, we reconsider what is already discussed in Eddington (1913, 1940), Malmquist (1922), Jeffreys (1938), Akritas & Bershady (1996), Kelly (2007), Andreon & Bergé (2012), Sereno & Ettori (2015a), and references therein. In this section, we neglect measurement uncertainties for simplicity.

Let us consider linear relations. We denote the intrinsic property as Z and its scattered proxy as X . For a given Z , the expected value of X is

$$\langle X|Z \rangle = \alpha_{X|Z} + \beta_{X|Z}Z, \quad (1)$$

where $\alpha_{X|Z}$ and $\beta_{X|Z}$ are the normalization and the slope of the X – Z scaling relation, respectively. The intrinsic normal scatter is indicated as $\sigma_{X|Z}$.

Let Y be a second proxy related to Z similarly to equation (1). Here, we take for simplicity the intrinsic scatter of Y given Z , $\sigma_{Y|Z}$, to be uncorrelated from X .

If the variable Z is normally distributed with mean μ_Z and standard deviation σ_Z , the total probability distribution can be written as

$$p(X, Y, Z) = \mathcal{N}(Z|\mu_Z, \sigma_Z) \mathcal{N}(X|\alpha_{X|Z} + \beta_{X|Z}Z, \sigma_{X|Z}) \\ \times \mathcal{N}(Y|\alpha_{Y|Z} + \beta_{Y|Z}Z, \sigma_{Y|Z}), \quad (2)$$

where $\mathcal{N}(x|\mu, \sigma)$ is the Gaussian distribution of the variable x with mean μ and variance σ^2 . In this basic picture, the distribution of Z depends on the selection criteria and how we assembled the sample. On the other hand, the scalings between Y – Z or X – Z express the physical relationships between the cluster observables and can be seen as intrinsic. We expect to see the same scaling between Y and Z independently on how Z was chosen. This picture is simplified since the scaling parameters and the scatter affecting the relation Y – Z might depend on Z , and, consequently, on the selection criteria. Scaling parameters may depend on redshift and mass. For example, the relation between the gas and the total mass in galaxy clusters is steeper at the low-mass end and the scatter is usually smaller for relaxed clusters (Mantz et al. 2016; Lovisari et al. 2020; Sereno et al. 2020).

In a standard observational set-up, we do not have direct access to Z (e.g. the true mass), but we can measure X (e.g. the optical richness) and Y (e.g. the WL mass), which are distributed as a bivariate Gaussian (see Appendix A),

$$p(X, Y) = \mathcal{N}^{(2)}(\{X, Y\} | \{\mu_X, \mu_Y\}, \Sigma_{XY}), \quad (3)$$

where $\mathcal{N}^{(2)}$ is the bivariate Gaussian distribution and Σ_{XY} is the scatter covariance matrix. The degree of correlation between X and Y , ρ_{XY} , depends on how much the distribution in Z is spread with respect to the intrinsic scatters. The broader the distribution, the less

¹The package `lira` is publicly available from the Comprehensive R Archive Network at <https://cran.r-project.org/web/packages/lira/index.html>. For further details, see Sereno (2016).

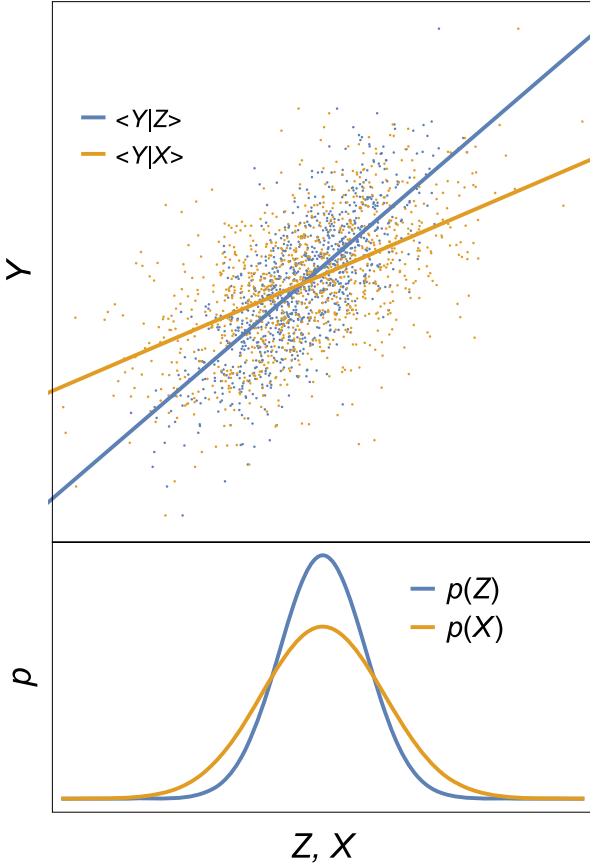


Figure 1. Conditional scaling relations for scattered proxies in arbitrary units. Z (turquoise) is the latent variable, which Y and X (orange) are scattered proxies of. Due to scatter, the distribution of X is more extended than Z (lower panel) and the scaling relation tracing the mean probability of Y given X , $\langle Y|X \rangle$, is flatter than $\langle Y|Z \rangle$ (upper panel).

(relatively) important the effect of the intrinsic scatters, and the more correlated X and Y are. The distribution of the pair $\{Y, Z\}$ is compared to the distribution of $\{Y, X\}$ in Fig. 1 for the case of sizeable intrinsic scatters $\sigma_{X|Z}$ and $\sigma_{Y|Z}$ with respect to dispersion of the Z distribution, σ_Z .

Alternatively, the probability of X and Y can be expressed in terms of the conditional probability of Y given X (see Fig. 1). This is practical when we forecast the unknown value of Y for a given known value of X . As showed in Appendix A,

$$p(X, Y) = \mathcal{N}(Y|\alpha_{Y|X} + \beta_{Y|X}X, \sigma_{Y|X})\mathcal{N}(X|\mu_X, \sigma_X). \quad (4)$$

Whereas the relation between X and Z (or Y and Z) depends on the involved physics only, the relation between X and Y is not universal and depends on the sample of Z that we are considering through the parameters μ_Z and σ_Z . The mean μ_Z affects the normalization $\alpha_{Y|X}$; the scatter σ_Z affects the normalization $\alpha_{Y|X}$, the slope $\beta_{Y|X}$, and the conditional scatter $\sigma_{Y|X}$ (see equations A9–A11).

2.1 Parameter degeneracies

Let us consider observations of galaxy clusters. The true mass can play the role of Z , as a latent variable we do not have direct access to. We can estimate the X-ray mass assuming equilibrium or the WL mass, and we can measure some other properties, e.g. the optical

richness or the X-ray luminosity. These are all scattered proxies of the true mass and can play the role of X or Y .

The inversion problem of determining $P(X, Y, Z)$ from $P(X, Y)$ is severely underconstrained. For Gaussian distributions, we want to determine eight parameters, i.e. $\alpha_{X|Z}$, $\beta_{X|Z}$, $\sigma_{X|Z}$, $\alpha_{Y|Z}$, $\beta_{Y|Z}$, $\sigma_{Y|Z}$, and μ_Z and σ_Z (see equation 2), from the measurements of five observables, i.e. $\alpha_{Y|X}$, $\beta_{Y|X}$, $\sigma_{Y|X}$, μ_X , and σ_X (see equation 4).

The Y – Z and X – Z scalings cannot be unambiguously determined. Even in the very favourable case of negligible intrinsic scatter ($\sigma_{X|Z} \ll \sigma_Z$), we can only measure the ratio of the slopes with respect to Z and a renormalized difference between the intercepts,

$$\beta_{Y|X} \simeq \frac{\beta_{Y|Z}}{\beta_{X|Z}}, \quad (5)$$

$$\alpha_{Y|X} \simeq \alpha_{Y|Z} - \alpha_{X|Z} \frac{\beta_{Y|Z}}{\beta_{X|Z}}. \quad (6)$$

In practical cases, we can often assume that one scaling, i.e. between X and Z , is known. For example, if we are studying a randomly oriented sample of relaxed clusters, the WL mass (X) is an unbiased proxy of the true mass (Z), with $\beta_{X|Z} = 1$ and $\alpha_{X|Z} = 0$. Under this condition, $\mu_X = \mu_Z$. Only the intrinsic scatter $\sigma_{X|Z}$ has still to be measured. In the following, we will assume that $\beta_{X|Z} = 1$ and $\alpha_{X|Z} = 0$ if not otherwise stated.

Even if the scaling between X and Z is fixed, residual degeneracies still hamper the inversion problem. When the conditional intrinsic scatter is sizeable with respect to the dispersion in Z ($\sigma_{X|Z} \sim \sigma_Z$), as can be the case when we study scaling relations for the optical properties of clusters selected in a narrow mass range, the Y – X relation can be significantly flatter than the Y – Z relation (see Fig. 1). This is a result of the magnitude-dependent Malmquist bias (Eddington 1913; Malmquist 1922; Jeffreys 1938; Eddington 1940; Butkevich, Berdyugin & Teerikorpi 2005; Sereno & Ettori 2017). Due to the scatter between X and Z , the marginalized distribution in X , $P(X)$, has a larger dispersion than $P(Z)$,

$$\sigma_X^2 = \sigma_Z^2 + \sigma_{X|Z}^2, \quad (7)$$

which flattens the slope of the Y – X relation. The larger the scatter $\sigma_{X|Z}$, the flatter the Y – X relation,

$$\beta_{Y|X} = \beta_{Y|Z} \left(1 - \frac{\sigma_{X|Z}^2}{\sigma_X^2} \right). \quad (8)$$

A degeneracy between the slope $\beta_{Y|Z}$ and the scatter $\sigma_{X|Z}$ then persists.

When we consider samples on a more extended range, e.g. spanning from the group scale to the more massive haloes, the Y – X relation is steeper with a larger absolute value of $\beta_{Y|X}$ than for limited samples in narrow Z ranges. According to our simplified picture, the relation Y – Z is universal, whereas the relation Y – X depends on the properties of the sample.

There can also be a remaining degeneracy between the slope $\beta_{Y|Z}$ and the normalization $\alpha_{Y|Z}$,

$$\alpha_{Y|X} = \alpha_{Y|Z} + (\beta_{Y|Z} - \beta_{Y|X})\mu_X. \quad (9)$$

This degeneracy can be reduced with convenient unit of measurements for X such that $\mu_X \sim 0$.

We may want to study the scatter and the properties of the measurable quantities X and Y with respect to the latent Z (e.g. the true mass, which is hidden to observations). This problem can be tackled with suitable priors or assumptions but, if we cannot directly measure Z and σ_Z , the determination of the intrinsic scatters, $\sigma_{Y|Z}$ and $\sigma_{X|Z}$, is underconstrained; see Fig. 2, where we are considering

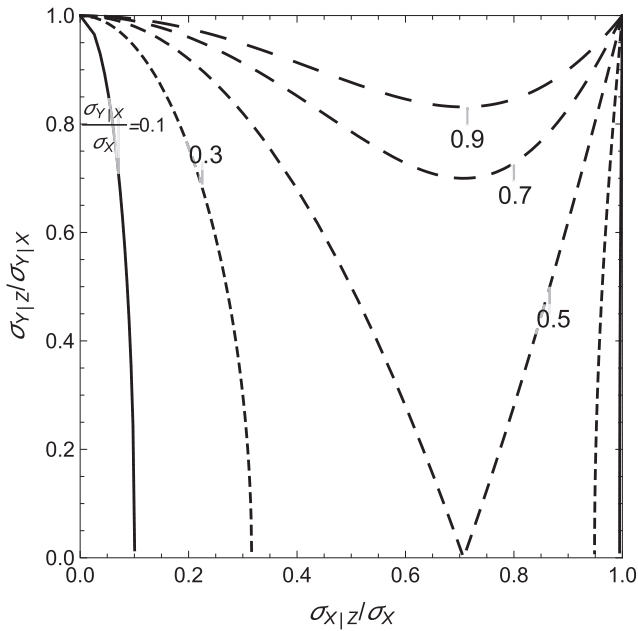


Figure 2. Degeneracy problem in measuring the intrinsic scatters of two variables X and Y , with respect to a third, hidden variable Z . The parametric plot shows $\sigma_{X|Z}$ (in units of the observable σ_X) and $\sigma_{Y|Z}$ (in units of the observable $\sigma_{Y|X}$) for σ_Z spanning the range from 0 to σ_X . The contours are for values of $\sigma_{Y|X}/\sigma_X$ from 0.1 to 0.9 in steps of 0.2. Here, we are considering $\beta_{Y|Z} = \beta_{X|Z} = 1$. Smaller values of $\sigma_{X|Z}/\sigma_X$ correspond to larger values of $\sigma_Z/\sigma_X = (1 - \sigma_{X|Z}^2/\sigma_X^2)^{1/2}$.

the simplified case with $\beta_{Y|Z} = \beta_{X|Z} = 1$. From the analysis of the distribution of X and Y , we can constrain two independent standard deviations, e.g. $\sigma_{Y|X}$ and σ_X , but not all the three quantities that we are interested in, i.e. σ_Z , $\sigma_{Y|Z}$, and $\sigma_{X|Z}$.

The value of the ratio $\sigma_{Y|X}/\sigma_X$ can be determined by observations, and the locus of possible solutions for the intrinsic scatters is then determined, i.e. one of the lines in Fig. 2, each one corresponding to a given value of the observable ratio. Each pair of (renormalized) values of $\sigma_{Y|Z}$ and $\sigma_{X|Z}$ that lie along the degeneracy locus is compatible with observations. Observations can determine the line where the intrinsic scatters lie in the parameter space shown in Fig. 2 (e.g. the full, dashed, or long-dashed ones), but we cannot break the degeneracy along the line. The solution is even more complicated if the scatters in X and Y are correlated.

If the variable X is not scattered ($\sigma_{X|Z} = 0$), then $\sigma_Z = \sigma_X$, and the scatter $\sigma_{Y|X}$ is equal to $\sigma_{Y|Z}$ (top left corner in Fig. 2). This corresponds to the case of X being an unscattered proxy of Z . If the Z distribution collapses to the Dirac delta function ($\sigma_Z \rightarrow 0$), then the scatter σ_X equals the conditional scatter $\sigma_{X|Z}$, and $\sigma_Y = \sigma_{Y|Z}$, or equivalently, $\sigma_{Y|Z} = \sigma_{Y|X}$ (top right corner in Fig. 2).

The degeneracy can be partially broken by an optimized set-up. If we are studying a scaling relation, we are likely studying a convenient sample where we are confident (based e.g. on external information) that the intrinsic scatter is smaller than the dispersion of the sample ($\sigma_{X|Z} < \sigma_X$) and that the intrinsic scatter of Y given X ($\sigma_{Y|X}$) is of the same order as, even though a bit smaller than, $\sigma_{Y|Z}$, the intrinsic property we want to infer. In practice, we have to confine ourselves to the upper left corner of the parametric space shown in Fig. 2 to better constrain the intrinsic scatters.

Suitable priors can also limit the parameter degeneracies. This can be the case for non-informative priors too. Priors for positive defined

quantities that are nearly constant in the log space, i.e. $P_{\text{prior}}(\log \sigma_{X|Z}) \sim \text{constant}$ over an extended parameter domain, are regarded as non-informative since they allow for very large or small scatters. Nevertheless, these priors slightly favour smaller values of $\sigma_{Y|Z}$, $P_{\text{prior}}(\sigma_{X|Z}) \sim 1/\sigma_{X|Z}$, and e.g. the left-hand side of Fig. 2. As prior for the variances, we adopt an inverse Gamma distribution (CoMaLit-II).

3 STACKING

For most samples of galaxy clusters, we are provided with reliable measurements of some properties, e.g. position, redshift, luminosity, but other properties, e.g. the WL mass, cannot be accurately measured for individual clusters. We then add the signal of the clusters that are similar with regard to one measured property to estimate the mean value of the property we cannot individually measure. For example, we can measure the optical richness of individual optically selected clusters, but not the WL signal that has to be recovered from the stacked signal of a subsample of objects with similar values of richness.

Let X be the proxy we can individually measure and Y the proxy we want to constrain. We stack the signal produced by all the clusters with $X_{\min,i} < X \leq X_{\max,i}$, where $X_{\min,i}$ and $X_{\max,i}$ are the lower and upper boundaries of the i th bin, respectively. We end up with a sample of known mean values, $\{\bar{X}_i, \bar{Y}_i\}$. Assuming that all clusters are weighted only by their number,

$$\bar{X}_i = \frac{\int_{X_{\min,i}}^{X_{\max,i}} X p(X) dX}{\int_{X_{\min,i}}^{X_{\max,i}} p(X) dX}, \quad (10)$$

$$\bar{Y}_i = \frac{\int_{-\infty}^{+\infty} \int_{X_{\min,i}}^{X_{\max,i}} Y p(X, Y) dX dY}{\int_{X_{\min,i}}^{X_{\max,i}} p(X) dX}. \quad (11)$$

By definition, \bar{Y}_i is the expected value for a given bin, i.e. for a given \bar{X}_i . For the normal distributions discussed in Section 2,

$$\bar{X}_i = \mu_X + \sigma_X^2 \frac{\mathcal{N}(X_{\min,i} | \mu_X, \sigma_X) - \mathcal{N}(X_{\max,i} | \mu_X, \sigma_X)}{\frac{1}{2} \left[\text{erf} \left(\frac{X_{\max,i} - \mu_X}{\sqrt{\sigma_X}} \right) - \text{erf} \left(\frac{X_{\min,i} - \mu_X}{\sqrt{\sigma_X}} \right) \right]},$$

$$\bar{Y}_i = \alpha_{Y|X} + \beta_{Y|X} \bar{X}_i. \quad (12)$$

We assume that the intrinsic scatter $\sigma_{Y|X}$ is constant and uncorrelated. Then, \bar{Y}_i is affected by an intrinsic scatter $\sigma_{\bar{Y}_i} = \sigma_{Y|X}/\sqrt{N_{\text{stack},i}}$, where $N_{\text{stack},i}$ is the number of clusters in the i th bin.

The sample $\{\bar{X}_i, \bar{Y}_i\}$ depends on the binning scheme, i.e. how we choose the boundaries of the intervals in X . The distribution $p(\bar{X}, \bar{Y})$ can differ from the unbinned $p(X, Y)$. They are equivalent if we choose the binning in such a way that $p(\bar{X})$ follows $p(X)$, and, as a consequence, the relations $\bar{Y} - \bar{X}$ and $Y - X$ are equivalent, i.e. for linearly related proxies, $\alpha_{\bar{Y}|\bar{X}} = \alpha_{Y|X}$ and $\beta_{\bar{Y}|\bar{X}} = \beta_{Y|X}$. This is the case if the bin boundaries are quantiles of $p(X)$.

Binning in quantiles can be unpractical if the signal-to-noise ratio (SNR) in the low-value bins is too small for a precise measurement of \bar{Y} . If X is the logarithm of some cluster property, e.g. the optical richness, and the signal is linear, i.e. it is proportional to 10^X , the SNR of the i th bin can be written as

$$\text{SNR}_i \propto \sqrt{N_{\text{stack},i}} (10^X)_i, \quad (13)$$

where we have assumed that the noise per cluster is constant and uncorrelated. It can be convenient to stack the data in such a way that the SNR is constant per bin in order to keep the relative uncertainty constant too.

To quantify how much the binning scheme hampers the recovery of the underlying $p(Y|X)$ distribution, we run 10^2 simulations, each one with $N_{cl} = 10^3$ clusters. Here, we distinguish the proxy X from the result of the measurement process x , which differs from X for the statistical uncertainty δx . In analogy, we define Y and y . The measurement results for the stacked quantities \bar{X} and \bar{Y} are \bar{x} and \bar{y} , respectively.

We set the underlying distribution of Z as a normal distribution with $\mu_Z = 0$ and $\sigma_Z = 0.25$. The proxy X is randomly distributed around Z with $\alpha_{X|Z} = 0$, $\beta_{X|Z} = 1$, and $\sigma_{X|Z} = 0.1$. The observed x were randomly distributed around X assuming a constant statistical uncertainty of $\delta x = 0.1/\ln(10)$. The second proxy y is produced similarly to x .

Finally, we assume that the statistical uncertainties on the stacked \bar{y}_i are inversely proportional to the bin SNR, and $\delta\bar{y} = 0.1/\ln(10)$ when $\text{SNR} = S_{\text{tot}}/N_{\text{bin}}/\sqrt{N_{\text{cl}}/N_{\text{bin}}}$, where $S_{\text{tot}} = \sum_{j=1}^{N_{\text{cl}}} 10^j$.

We stack the data in $N_{\text{bin}} = 10$ bins defined according to the measured x . The bins are chosen such that (i) $p(\bar{x})$ follows $p(x)$, i.e. the bin boundaries are quantiles of $p(x)$; (ii) the bins are equally spaced, i.e. $\Delta x_i = x_{\text{max},i} - x_{\text{min},i} = \text{constant}$; and (iii) the SNR per bin is constant.

Results are summarized in Fig. 3. The regression exploits a Bayesian inference method with non-informative priors; see Appendix C, where we consider the variable Y as a scattered proxy of the measured X . Since we are interested in the conditional probability of Y given X , we fit only two variables (X and Y) and we neglect the latent Z . In the `lira` fitting, we identify X as Z , i.e. we put $\alpha_{X|Z} = 0$, $\beta_{X|Z} = 1$, and we neglect the scatter $\sigma_{X|Z}$ (see Appendix C). The parameters of the scaling relation between X and Y are well recovered from the stacked data. This is expected for the properties of the stacked technique, for which $Y_i = \langle Y|X_i \rangle$ by design. Moreover, we find that the intrinsic scatter can be recovered for all binning schemes without any significant bias. The impact of the binning scheme is then negligible in most practical cases, and we can optimize the scheme to increase the statistical accuracy in the measurement of \bar{Y} .

4 RECONSTRUCTION

In this section, we describe a three-step procedure to recover the distribution $p(X, Y|Z)$ of two scattered proxies X and Y of an underlying property Z based on stacked data, $\{\bar{x}, \bar{y}\}$, and the distribution of one individually measured proxy, $p(x)$.

We first fit the stacked data to recover the conditional $p(Y|X)$. This is done as described in Section 3. As a result of the regression, we constrain the parameters of the scaling relation, $\alpha_{Y|X}$ and $\beta_{Y|X}$, and the scatter $\sigma_{Y|X}$.

As a second step, we generate a fictitious population of y based on the observed x and on the conditional $p(Y|X)$ derived in the first step. Given each observed x , we draw a fictitious Y_f , thanks to $P(Y|X)$. Since we are using x instead of X , we associate an uncertainty $\delta y_f = |\beta_{Y|X}|\delta x$. The correlation between δx and δy_f is $\beta_{Y|X}/|\beta_{Y|X}|$. If the results of the first step are in the form of a Monte Carlo chain, each y_f can be extracted by adopting a set of parameters of the Y - X relation randomly drawn from the chain.

As a third and final step, we fit the observed x and the fictitious y_f to recover the relations of the proxies with the latent Z , i.e. the parameters that characterize $p(X, Y|Z)$.

To test the procedure, we run 10^2 simulations, each one with $N_{cl} = 10^3$ data points, with the same set-up described in Section 3. For comparison, we also consider the case when the proxy Y can be measured with good precision for single objects. In this case, the observed y are randomly distributed around Y assuming a constant

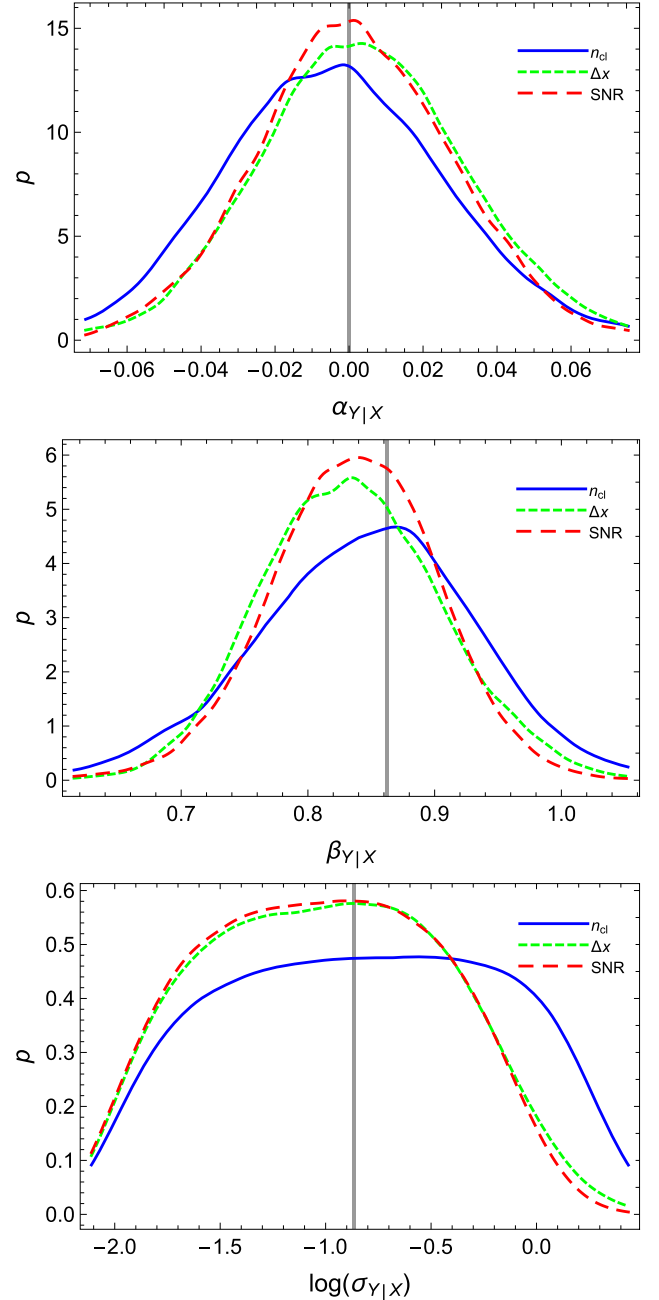


Figure 3. Probability density functions of the parameters of the conditional scaling relation $Y|X$ recovered from a sample of 10 simulated stacked data $\{\bar{X}_i, \bar{Y}_i\}$. Results are averaged over 10^2 mocks. The full blue line, the short-dashed green line, and the long-dashed red line refer to a binning scheme that is uniform for number of clusters per bin, interval length, or bin SNR, respectively. The vertical grey lines mark the input parameters. From the top to the bottom panel, we plot the a posteriori marginalized probability of normalization $\alpha_{Y|X}$, slope $\beta_{Y|X}$, and scatter $\sigma_{Y|X}$.

statistical uncertainty of $\delta y = 0.1/\ln(10)$. Since data samples of WL cluster masses consist usually of a few dozens, we consider the fitting of a random subset of 10^2 fictitious data points or a sample of measured y of the same size.

Results are summarized in Table 1 and Fig. 4, where we compare results when the values of y are either directly observed for individual clusters (y observed) or recovered from the stacked data (y

Table 1. Parameters of the scaling relations Y – Z and X – Z as recovered from simulated stacked data. Column 1: parameter name. Column 2: input value. Column 3: results of fitting when the y values are measured for individual objects. Column 4: scaling parameters as derived from stacked data by fitting a population of fictitious y produced with the method of Section 4.

Parameter	Input	y observed	y recovered
$\alpha_{Y Z}$	[0]	0.00 ± 0.02	0.00 ± 0.04
$\beta_{Y Z}$	[1]	1.00 ± 0.16	1.04 ± 0.33
$\sigma_{Y Z}$	[0.1]	0.09 ± 0.05	0.13 ± 0.11
$\sigma_{X Z}$	[0.1]	0.09 ± 0.05	0.11 ± 0.07
μ_Z	[0]	0.00 ± 0.04	0.00 ± 0.04
σ_Z	[0.25]	0.25 ± 0.03	0.24 ± 0.05

recovered³). The reconstruction method can recover the intrinsic parameters but with larger statistical uncertainties than the ideal fitting to observed data, even though this estimated precision is driven by our arbitrary choice for the statistical uncertainties δy and $\delta \bar{y}$. The smaller the statistical uncertainties, the better the precision that the scatter can be recovered to.

5 A TEST CASE: THE AMICO-KIDS CLUSTERS

We apply our procedure to the catalogue of galaxy clusters detected with the optimal filtering algorithm AMICO (Bellagamba et al. 2018; Maturi et al. 2019) in the sky area covered by the KiDS DR3 (de Jong et al. 2013; Kuijken et al. 2015; de Jong et al. 2017). KiDS-DR3 covers $\sim 440 \text{ deg}^2$ in four optical bands u , g , r , and i , down to the limiting magnitudes (calculated as 5σ in a 2 arcsec aperture) of 24.3, 25.1, 24.9, and 23.8, respectively (de Jong et al. 2017).

The catalogue comprises 8092 candidate clusters at redshifts $z < 0.8$ (Radovich et al. 2017; Maturi et al. 2019). The 6961 objects in the redshift range $0.1 < z < 0.6$ were mass calibrated in Bellagamba et al. (2019), who performed a WL stacked analysis by binning clusters according to redshift and two different mass proxies, namely the amplitude A (the returned signal amplitude of the optimal filtering procedure) and the richness λ_* (the sum of membership probabilities). The mass range of the detected clusters extends over more than one order of magnitude, down to $M_{200} \lesssim 10^{13} M_\odot$. In the following, we exploit the WL mass estimates of Bellagamba et al. (2019), M_{WL} , but we extend the analysis of the mass–observable relation to estimate the intrinsic scatter.

Following the notation of the previous sections, we define the scattered proxies X and Y as

$$X = \log(\lambda_*/30), \quad (14)$$

$$Y = \log(M_{\text{WL}}/M_\odot/10^{14}), \quad (15)$$

$$Z = \log(Z_{\lambda_*}/30), \quad (16)$$

where Z is the unscattered latent variable, which X and Y are scattered proxies of. The property Z_{λ_*} can be thought of as the richness we would measure if there was no intrinsic scatter in the true mass–richness relation. We consider X as unbiased; i.e. we fix the scaling parameters to $\alpha_{X|Z} = 0$ and $\beta_{X|Z} = 1$. The variables X and Y differ from their measured values x and y for statistical uncertainties or systematic errors (see Appendix B). We first fit the stacked relation in order to infer the estimated WL mass of a cluster given its richness. Clusters are grouped in bins of approximately equal SNR, with the number of clusters per bin ranging from more than 1000 for the low-richness bins to a few dozens for the large richness bins (see table 3 of Bellagamba et al. 2019). In addition to the statistical uncertainty

on the estimation of the stacked WL mass, we consider a systematic error of 7.6 per cent due to impure selection of background galaxies, photometric redshift estimates, shear measurements, projection effects, and halo modelling (Bellagamba et al. 2019).

Projection effects or orientation bias can play a major role in both WL mass estimates and cluster detection. The processes of optical cluster selection and richness estimation can be biased, leading to stacking of structures that are preferentially elongated along the line of sight. WL masses can then be overestimated (Dietrich et al. 2014). These effects can make the intrinsic scatters of WL mass and richness at a given true mass correlated. Unfortunately, degeneracy effects (see Section 2) prevent a full recovery of the scatter correlation, whose analysis would need the joint comparison of multiple proxies (Farahi et al. 2019; Sereno et al. 2020). In the following, we neglect the correlation between the intrinsic scatters of WL mass and richness.

The expected value of Y given X is expressed as (CoMaLit-IV),

$$\langle Y|X \rangle = \alpha_{Y|X} + \beta_{Y|X} X + \gamma_{Y|X} \log F_z, \quad (17)$$

where α denotes the normalization, the slope β accounts for the dependence on Z , and the slope γ accounts for the redshift evolution. F_z is the renormalized Hubble parameter, $F_z = E_z/E_z(z_{\text{ref}})$. For the AMICO-KiDS-DR3 sample, we fix $z_{\text{ref}} = 0.35$, close to the mean redshift of the full sample. At a given X , Y is distributed around X with a scatter $\sigma_{Y|X}$, which we assume to be constant.

Results are summarized in Table 2 and Fig. 5. The scaling parameters are in agreement with Bellagamba et al. (2019). The large number of clusters per bin makes the effective scatter small, so that concurring scaling parameters α and β can be recovered notwithstanding the fitting method. In particular, Bellagamba et al. (2019) did not have to consider the scatter as a model parameter. However, thanks to the regression procedure described here, we can fit the intrinsic scatter too. We find that the richness is an excellent mass proxy. The intrinsic scatter of the WL mass of a single cluster at a given richness is $\sigma_{m_{\text{WL}}|\lambda_*} = 18 \pm 22$ per cent, with a marginalized probability distribution in linear space $p(\sigma_{m_{\text{WL}}|\lambda_*})$ peaked at very low values and with an extended tail at large values. The probability that the scatter is lower than 10 (or 5) per cent is ~ 35 (or 17) per cent. Since the posterior probability distribution is skewed with an extend tail, the logarithm (in base 10) of the biweight estimator of the conditional scatter, $\log(\text{CBI}[\sigma_{m_{\text{WL}}|\lambda_*}]) \sim -0.7$, is significantly larger than the biweight estimator of the logarithms, $\text{CBI}[\log(\sigma_{m_{\text{WL}}|\lambda_*})] \sim -1.1$; see Table 2.

We then reconstruct the scattered distribution of the WL masses based on the richness distribution. Results are summarized in Table 3 and Fig. 6. We find a low value for the intrinsic scatter of the richness, $\log(\sigma_{\lambda_*|Z_{\lambda_*}}) \sim -1.6$, which makes the slope $\beta_{Y|Z}$ similar to $\beta_{Y|X}$. Statistical uncertainties on the measured richness reported in the catalogue are of the order of ~ 20 per cent. They are estimated with the analysis of mock galaxy catalogues derived directly from the data to fully reproduce their statistical properties including photo- z uncertainties, unknown absorption across the survey, missing data, and spatial correlation of galaxies and galaxy clusters (Maturi et al. 2019). As a result, the formal statistical uncertainty accounts for projection effects too, which are one of the main sources of dispersion. If this major contribution is treated as a source of statistical uncertainty, it does not contribute to the intrinsic scatter of the richness, which we find to be small.

6 MASS PROXIES

Based on the AMICO richness, the mass of the clusters in the KiDS DR3 can be determined to a ~ 20 per cent precision. This result cannot

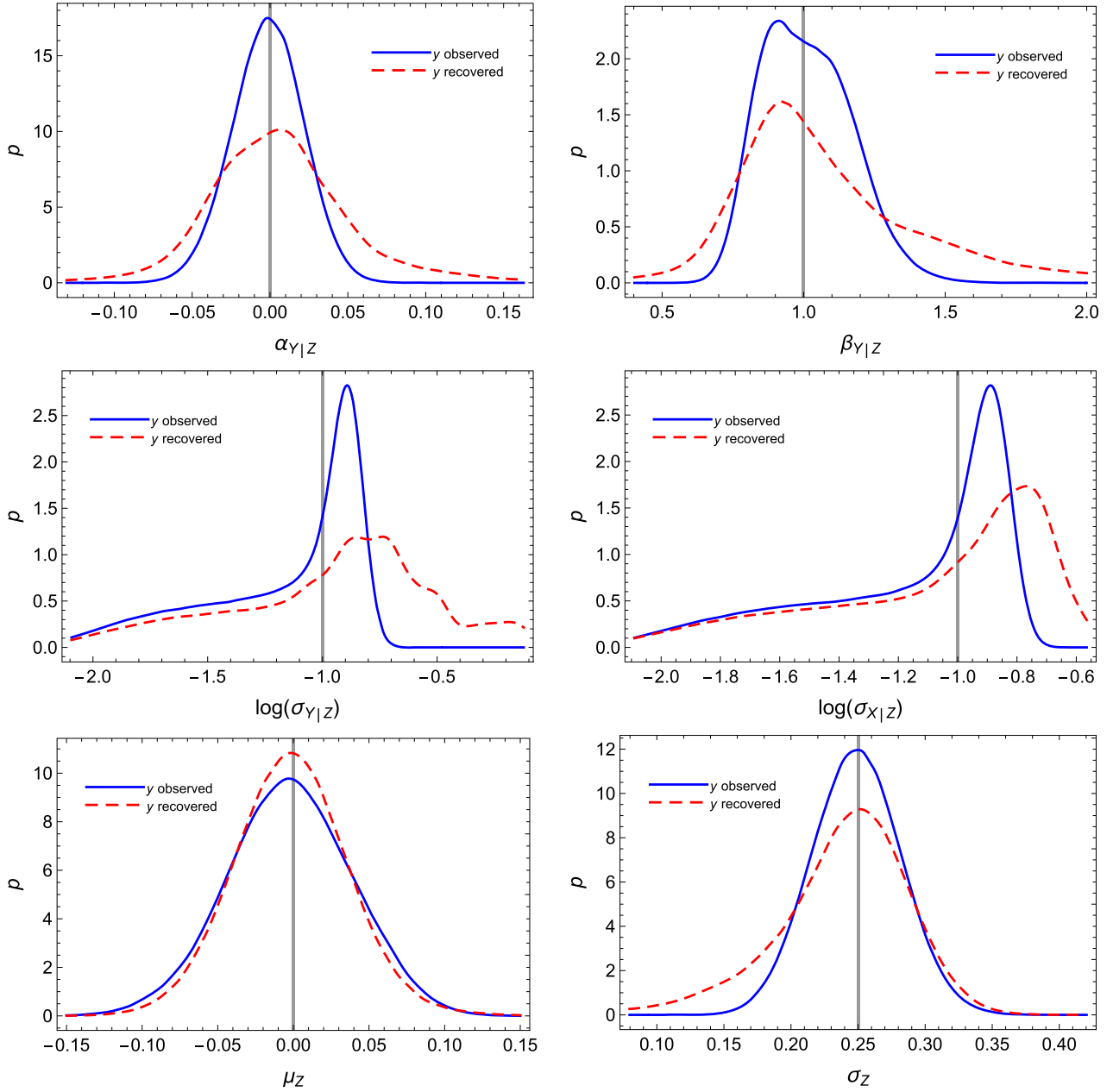


Figure 4. Probability density functions of the parameters of the scaling relations Y - Z and X - Z recovered from a simulated sample of 10 stacked data $\{\bar{X}_i, \bar{Y}_i\}$. Results are averaged over 10^2 mocks. The full blue line and the dashed red line refer to the fitting of y values that are either observed for individual clusters (y observed) or reconstructed from the stacked data (y recovered), respectively. The vertical grey lines mark the input parameters. We plot the a posteriori marginalized probability of the normalization $\alpha_{Y|Z}$ (top left), of the slope $\beta_{Y|Z}$ (top right), of the intrinsic scatter $\sigma_{Y|Z}$ (middle left), of the intrinsic scatter $\sigma_{X|Z}$ (middle right), and of the mean μ_Z (bottom left) and standard deviation (bottom right) of the distribution $p(Z)$.

Table 2. Parameters of the conditional scaling relation (WL mass given optical richness) for the AMICO-KiDS-DR3 clusters.

Parameter	Observed
$\alpha_{m_{\text{WL}} \lambda_*}$	0.00 ± 0.04
$\beta_{m_{\text{WL}} \lambda_*}$	1.69 ± 0.08
$\gamma_{m_{\text{WL}} \lambda_*}$	-0.94 ± 0.60
$\log(\sigma_{m_{\text{WL}} \lambda_*})$	-1.13 ± 0.53

be compared to performances of other richness-based proxies. The richness somehow counts the number of galaxies in a cluster, but its definition depends on the measurement process. We can count galaxies in different magnitude ranges and aperture radii; we can look for red-sequence galaxies or galaxies with similar photometric redshifts. Furthermore, the performance of a proxy optimized on a calibration sample of well-selected clusters with high-quality data can be better than that for the very numerous candidate clusters found in a very large and shallow survey.

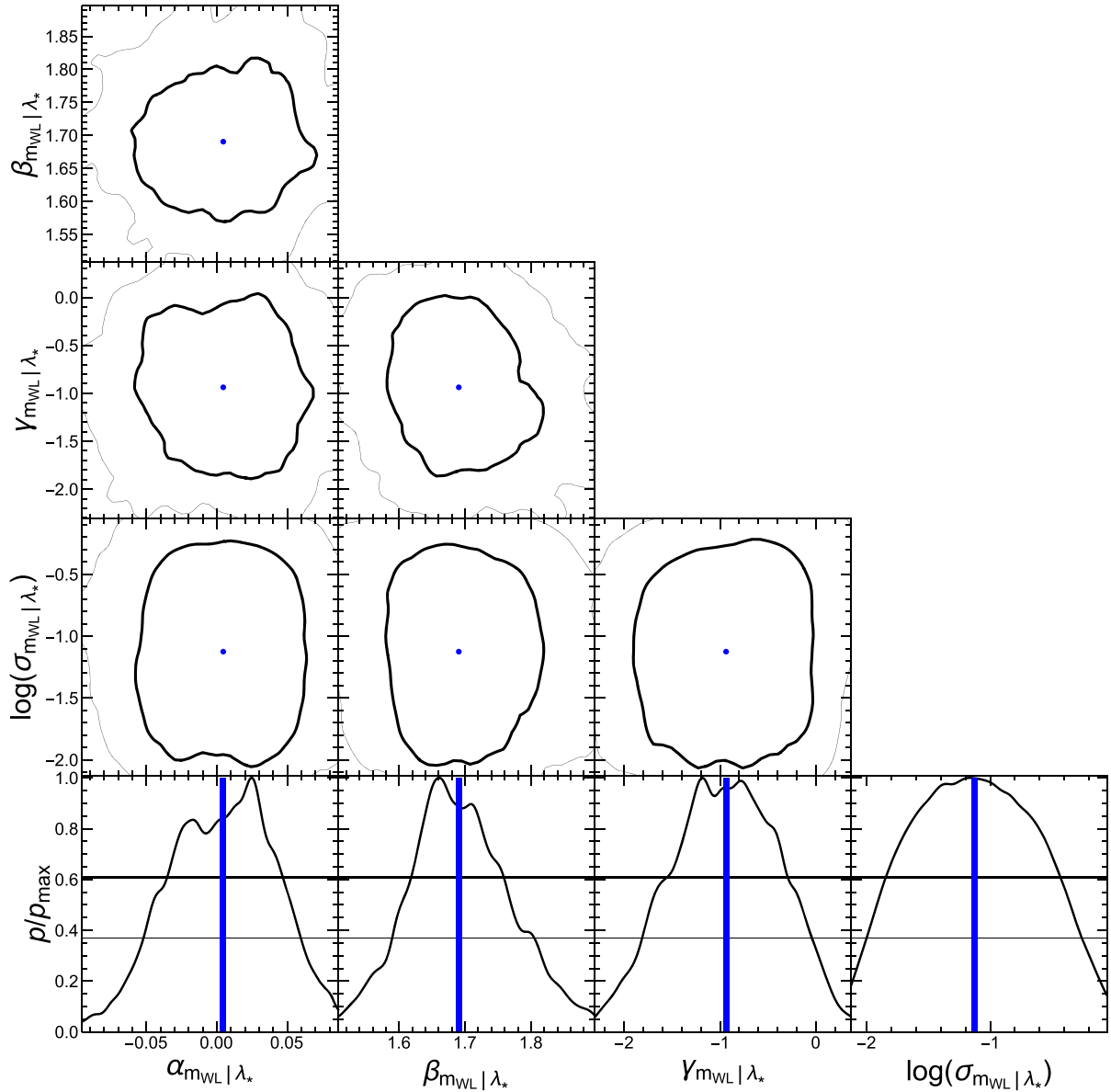


Figure 5. Probability distributions of the parameters of the scaling relation of the WL mass for a given richness of the clusters in the KiDS-DR3 AMICO catalogue. The intercept, slope, redshift evolution, and intrinsic scatter are denoted as α , β , γ , and σ , respectively. The thick and thin black contours include the 1σ and 2σ confidence regions in two dimensions, here defined as the regions within which the probability is larger than $\exp(-2.3/2)$ and $\exp(-6.17/2)$ of the maximum, respectively. The bottom row shows the marginalized 1D distributions, renormalized to the maximum probability. The thick and thin black horizontal lines denote the confidence limits in one dimension, i.e. $\exp(-1/2)$ or $\exp(-4/2)$ and of the maximum. The blue symbols mark the biweight estimator.

Table 3. Parameters of the scaling relations for the AMICO-KiDS-DR3 clusters when both the WL mass and the optical richness are considered as scattered proxies of a latent Z variable.

Parameter	Observed
$\alpha_{m_{\text{WL}} Z\lambda_*}$	0.00 ± 0.01
$\beta_{m_{\text{WL}} Z\lambda_*}$	1.70 ± 0.05
$\gamma_{m_{\text{WL}} Z\lambda_*}$	-0.97 ± 0.22
$\log(\sigma_{m_{\text{WL}} Z\lambda_*})$	-0.63 ± 0.01
$\log(\sigma_{\lambda_* Z\lambda_*})$	-1.63 ± 0.24

Even if a fair comparison cannot be performed, it can be still useful to review the performances of some richness estimators as mass proxy. Wen, Han & Liu (2012) identified overdensities of galaxies around the brightest cluster galaxies (BCGs) through their photometric redshifts. The optical richness is defined as the ratio of the total r -band luminosity within an empirically determined radius and the evolved characteristic galaxy luminosity. Based on a collection of 1191 clusters with masses estimated with either X-ray or SZ proxies, they found that the mass of the 132 684 candidate galaxy clusters detected in the SDSS (Sloan Digital Sky Survey) DR12 can be estimated with a scatter of ~ 40 per cent (Wen & Han 2015).

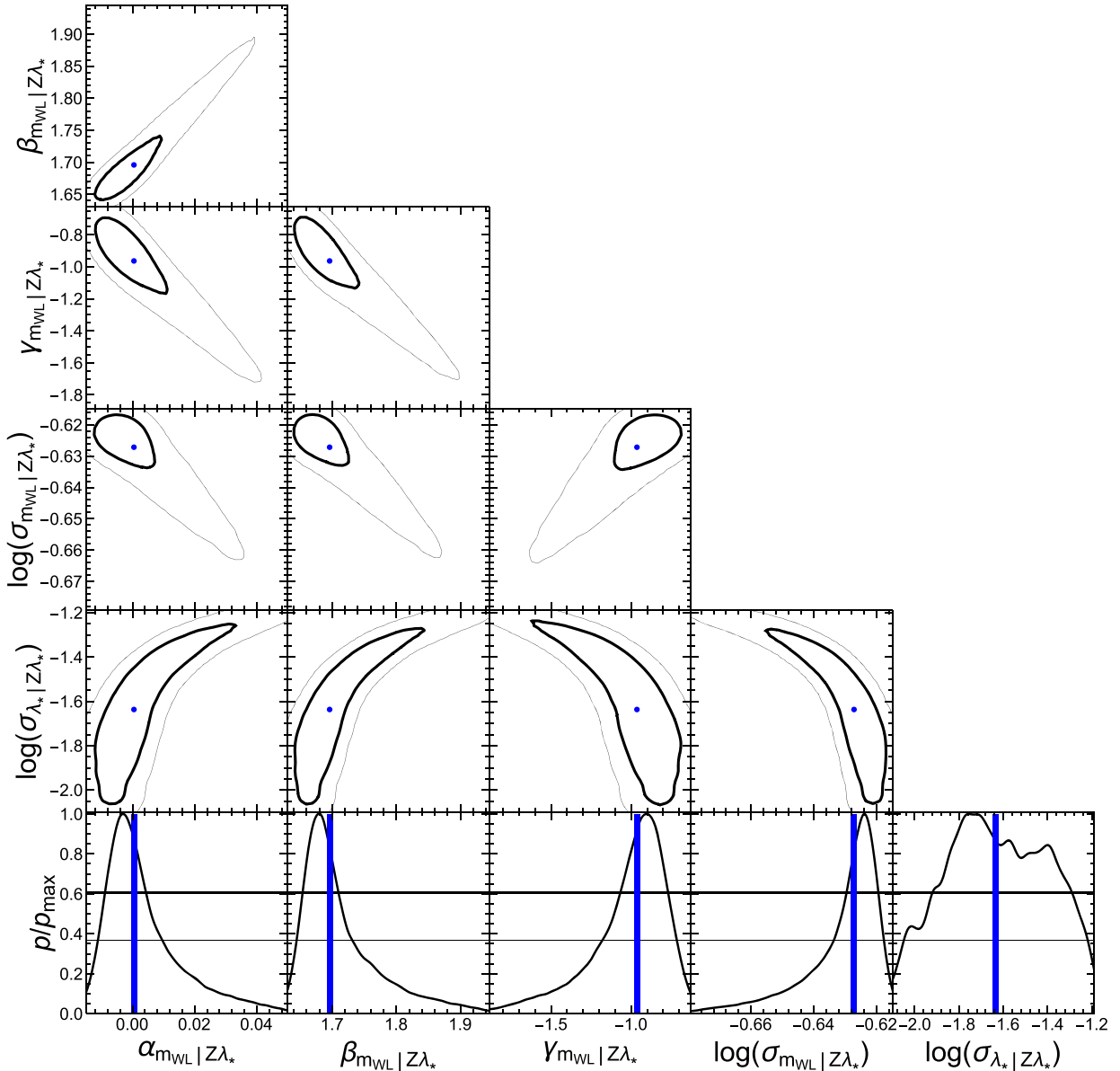


Figure 6. Probability distributions of the parameters of the scaling relation of the WL mass and richness for a given unscattered richness of the clusters in the KiDS-DR3 AMICO catalogue. The intercept, slope, redshift evolution, and intrinsic scatters are denoted as α , β , γ , and σ , respectively. The thick and thin black contours include the 1σ and 2σ confidence regions in two dimensions, here defined as the regions within which the probability is larger than $\exp(-2.3/2)$ and $\exp(-6.17/2)$ of the maximum, respectively. The bottom row shows the marginalized 1D distributions, renormalized to the maximum probability. The thick and thin black horizontal lines denote the confidence limits in one dimension, i.e. $\exp(-1/2)$ or $\exp(-4/2)$ of the maximum. The blue points and the blue vertical lines mark the biweight estimator.

Rykoff et al. (2012) considered a red-sequence-matched filter richness estimator implemented on the maxBCG cluster catalogue. Using the X-ray luminosity from the *ROSAT* All-Sky Catalogue as mass proxy, they found a scatter in mass at a fixed richness of ~ 20 – 30 per cent depending on the richness, and comparable to that for total X-ray luminosity.

The red-sequence Matched-filter Probabilistic Percolation (redMaPPer) algorithm is a photometric cluster finding algorithm that identifies galaxy clusters as overdensities of red-sequence galaxies (Rykoff et al. 2014). Rozo & Rykoff (2014) evaluated the performance of the SDSS DR8 redMaPPer photometric cluster catalogue by comparison to overlapping X-ray and SZ-selected catalogues from the literature. Based on the X-ray temperature–

richness and gas mass–richness relations, they estimated a mass scatter of ~ 25 per cent.

The CAMIRA (Cluster finding Algorithm based on Multiband Identification of Red-sequence gAlaxies) algorithm is a red-sequence cluster finder based on a stellar population synthesis model (Oguri 2014). Murata et al. (2019) adopted a forward modelling approach to fit the abundance and stacked lensing profiles of the CAMIRA clusters detected in the Hyper Suprime-Cam survey first-year data. They found that the scatter values of the mass at a given richness for the Planck model (~ 30 per cent) are systematically larger than those for the WMAP (Wilkinson Microwave Anisotropy Probe) model. They also found that the scatter values for the Planck model increase towards lower richness values, whereas those for the

WMAP model are consistent with constant values as a function of richness.

7 CONCLUSIONS

The potential of galaxy cluster number counts as cosmological probe can be fully exploited if the statistical properties of the sample are well characterized and if the mass calibration is accurate. In present and planned surveys, investigators have shown confidence that the completeness and purity of selected clusters can be well measured (Euclid Collaboration 2019). Uncertain mass calibration has been the designated scapegoat for inconclusive results (Planck Collaboration XXIV 2016b; DES Collaboration 2020). A proper treatment of scaling relation and mass calibration is then crucial to settle the question. WL masses are regarded as the most reliable mass estimates. Stacking enable us to calibrate the observable–mass relation down to the very low mass haloes discovered by large and deep surveys. This technique helps in studying the scaling parameters without extrapolation but can make some parameter estimations problematic. The intrinsic scatter should be derived from the data as well but it is usually constrained through strong priors, which could bias the cosmological inference if misplaced. In this paper, we have proposed a Bayesian method to infer the intrinsic scatter from stacked observable–mass relations.

Bayesian inference is a solid tool to infer unbiased physical quantities in problems with a large number of manifest or latent variables and parameter degeneracy. In the simplest case of uncorrelated data, the intrinsic scatter of the stacked signal from N_{stack} clusters scales as $N_{\text{stack}}^{-1/2}$ of the scatter of individual objects. However, some sources of scatters can be correlated and the variance of a cluster stack does not scale simply as $1/N_{\text{stack}}$. For example, the positions of galaxy clusters are correlated and the variance in the stacked WL signal due to uncorrelated structure decreases somewhat less steeply than $1/N_{\text{stack}}$ (McClintock et al. 2019). In this case, the scaling of the stacked scatter has to be properly weighted.

Whereas targeted observations are very expensive and feasible only for relatively small data samples (Postman et al. 2012; von der Linden et al. 2014; Steinhardt et al. 2020), mass proxies based on optical richness are cheap by design in large surveys and can provide accurate and precise masses even for small groups. As a test case, we applied our approach to the AMICO clusters in the KiDS survey. The method showed that the optical richness determined by the AMICO algorithm itself is a reliable mass proxy, with a scatter of ~ 20 per cent. This is comparable to the precision attainable with direct WL or X-ray mass measurements for very deep observations (CoMaLit-I).

The knowledge of the observable–cluster mass scaling relation is crucial to fulfil the potential of galaxy clusters as cosmological probes. Thanks to strong constraints on scatter and mass bias, constraints on dark energy from analyses of number counts and clustering can be significantly improved. Sartoris et al. (2016) showed that for a Euclid-like survey the figure of merit for the parameters of the dark energy equation of state increases by a factor of ~ 4 if the parameters of the scaling relation are accurately known. Precision cosmology requires that the scaling parameters and the scatter of the scaling relation are determined together with the cosmological parameters (Murata et al. 2019).

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DATA AVAILABILITY

The software `lira` is publicly available from the Comprehensive R Archive Network at <https://cran.r-project.org/web/packages/lira/index.html>.

The data underlying this article will be shared on reasonable request to the corresponding author.

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APPENDIX A: BIVARIATE NORMAL DISTRIBUTION

Let X and Y be two scattered proxies of Z . The marginalized bivariate normal distribution of X and Y can be written as

$$p(X, Y) = \mathcal{N}^{(2)}(\{X, Y\} | \{\mu_X, \mu_Y\}, \Sigma_{XY}), \quad (\text{A1})$$

where $\mathcal{N}^{(2)}$ is the bivariate Gaussian distribution, the mean values of X and Y are

$$\mu_X = \alpha_{X|Z} + \beta_{X|Z}\mu_Z, \quad (\text{A2})$$

$$\mu_Y = \alpha_{Y|Z} + \beta_{Y|Z}\mu_Z, \quad (\text{A3})$$

respectively, and the covariance matrix Σ_{XY} can be expressed as

$$\Sigma_{XY} = \begin{pmatrix} \sigma_X^2 & \rho_{XY}\sigma_X\sigma_Y \\ \rho_{XY}\sigma_X\sigma_Y & \sigma_Y^2 \end{pmatrix}, \quad (\text{A4})$$

with

$$\sigma_X^2 = \sigma_{X|Z}^2 + \beta_{X|Z}^2\sigma_Z^2, \quad (\text{A5})$$

$$\sigma_Y^2 = \sigma_{Y|Z}^2 + \beta_{Y|Z}^2\sigma_Z^2, \quad (\text{A6})$$

$$\rho_{XY} = \frac{1}{\left(1 + \frac{\sigma_{X|Z}^2}{\beta_{X|Z}^2\sigma_Z^2}\right)^{1/2} \left(1 + \frac{\sigma_{Y|Z}^2}{\beta_{Y|Z}^2\sigma_Z^2}\right)^{1/2}}. \quad (\text{A7})$$

The probability of X and Y can also be written in terms of the conditional probability of Y given X , thanks to the chain rule,

$$p(X, Y) = \mathcal{N}(Y|\alpha_{Y|X} + \beta_{Y|X}X, \sigma_{Y|X})\mathcal{N}(X|\mu_X, \sigma_X), \quad (\text{A8})$$

where

$$\alpha_{Y|X} = \mu_Y - \frac{\beta_{Y|Z}}{\beta_{X|Z}} \frac{\mu_X}{1 + \frac{\sigma_{X|Z}^2}{\beta_{X|Z}^2\sigma_Z^2}}, \quad (\text{A9})$$

$$\beta_{Y|X} = \frac{\beta_{Y|Z}}{\beta_{X|Z}} \frac{1}{1 + \frac{\sigma_{X|Z}^2}{\beta_{X|Z}^2\sigma_Z^2}}, \quad (\text{A10})$$

$$\sigma_{Y|X}^2 = \sigma_{Y|Z}^2 + \frac{\beta_{Y|Z}^2}{\beta_{X|Z}^2} \frac{\sigma_{X|Z}^2}{1 + \frac{\sigma_{X|Z}^2}{\beta_{X|Z}^2\sigma_Z^2}}. \quad (\text{A11})$$

The normalization and the scatter can be rewritten in a more compact form in terms of the slope $\beta_{Y|X}$ as

$$\alpha_{Y|X} = \mu_Y - \beta_{Y|X}\mu_X, \quad (\text{A12})$$

$$\sigma_{Y|X}^2 = \sigma_{Y|Z}^2 + \beta_{Y|X} \frac{\beta_{Y|Z}}{\beta_{X|Z}} \sigma_{X|Z}^2. \quad (\text{A13})$$

The probability of X given Y can be obtained from the above expression by inverting X and Y .

APPENDIX B: SYSTEMATIC ERRORS

The measured x and y and the latent values X and Y are related as

$$P(x_i, y_i | X_i, Y_i) \propto \mathcal{N}^2(\{X_i - \delta x_{\text{sys}}, Y_i - \delta y_{\text{sys}}\}, \mathbf{V}_{\delta,i}) \times \mathcal{H}(y_{\text{th},in}), \quad (\text{B1})$$

where \mathcal{H} is the Heaviside function, $\mathbf{V}_{\delta,n}$ is the covariance matrix of the i th cluster accounting for statistical uncertainties, and δx_{sys} and δy_{sys} are systematic uncertainties that affect all clusters in the same way.

The probability distribution is truncated for $y_{in} < y_{\text{th},in}$ to correct for the Malmquist bias if only clusters above the observational thresholds (in the response variables) are included in the sample (CoMaLit-II).

APPENDIX C: REPRODUCIBILITY OF THE RESULTS

To allow the reproducibility of our results, we provide the `lira` commands used in Section 5. Let `x` and `y`, `delta.x` and `delta.y`, `covariance.xy`, and `z` be the vectors storing the values of the observed x and y , their uncertainties δ_x and δ_y , the uncertainty covariances δ_{xy} , and the redshifts z , respectively. If not stated otherwise, priors and parameter values are set to default.

(i) For regressions of stacked data, without scatter on the X variable, the analysis is performed with the command

```
> mcmc <- lira (x, y, delta.x
= delta.x, delta.y = delta.y,
delta.y.sys='dnorm(0.0, (0.076/log(10.))^2)',
z = z, z.ref = 0.35, gamma.mu.Z.Fz=0.0,
gamma.sigma.Z.D = 'dt', n.chains = 4,
n.adapt = 5*10^3, n.iter = 5*10^4),
where the covariate distribution is modelled as a Gaussian function with redshift evolving mean and standard deviation (gamma.sigma.Z.D = 'dt'). Each of the n.chains = 4 chain was n.iter = 5 × 104 long, and the number of iterations for initialization was set to n.adapt = 5*103. The
```

prior on the systematic error on y is modelled as a zero-centred Gaussian with standard deviation of $0.076/\log(10)$.

(ii) For regressions with scatter on both the Y and the X variables, the analysis is performed with the command

```
> mcmc <- lira (x, y, delta.x = delta.x,
delta.y = delta.y, covariance.xy = covari-
ance.xy, z = z, z.ref = 0.35, sigma.XIZ.0
= 'prec.dgamma', gamma.mu.Z.Fz=0.0,
```

```
gamma.sigma.Z.D = 'dt', n.chains = 4,
n.adapt = 5*10^3, n.iter = 5*10^4),
where the argument sigma.XIZ.0 = 'prec.dgamma'
makes the scatter in  $X$  a parameter to be fitted with a prior on the
precision described by a Gamma distribution.
```

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